

Hawaii Ocean Time-series HOT-181 General Cruise Plan

Cruise ID: KM0614

Vessel: R/V *Kilo Moana*, University of Hawaii

Master of the Vessel: Captain Rick Myers

Chief Scientist: Fernando Santiago-Mandujano, University of Hawaii

OTG Marine Technicians: Kuhio Vellalos, Gabe Foreman

Loading: May 24, 2006 @ 0900 HST

Departure: May 25, 2006 @ 0900

Arrival: May 29, 2006 @ 0800

1.0 SCIENTIFIC OBJECTIVES

The objective of the cruise is to maintain a collection of hydrographic and biogeochemical data at the Hawaii Ocean Time-series (HOT) stations. Five stations will be occupied during the cruise, in the following order:

- 1) Station 1, referred to as Station Kahe, is located at 21° 20.6'N, 158° 16.4'W and will be occupied on the first day of the cruise for about 2 hours.
- 2) Station 2, referred to as Station ALOHA is defined as a circle with a 6 nautical mile radius centered at 22° 45'N, 158°W. This is the main HOT station and will be occupied during the 2nd, 3rd, and 4th days of the cruise.
- 3) Station 51, is the site of the MOSEAN Mooring, located at 22° 45'N, 158° 6'W will be occupied on the 4th day of the cruise for about 30 minutes.
- 4) Station 50, is the site of the WHOTS Mooring, located at 22° 46.1'N, 157° 53.4'W will be occupied on the 4th day of the cruise for about 30 minutes.
- 5) An underwater bottom camera will be deployed in transit to Station ALOHA, at 21° 54.1'N, 158° 16.5'W, and retrieved at the end of the cruise, the deployment will take 30 minutes, and the recovery operation will take 2.5 hours.

1.1 SCIENTIFIC OPERATIONS

<u>Station</u>	<u>Activities</u>
Kahe (sta. 1)	Weight Cast, PRR cast, CTD cast (1000 m)
ALOHA (sta. 2)	Sediment traps, net tows, CTD operations, primary productivity measurements, AC9/FRRf, deployment of two ARGO floats, misc. experiments.
MOSEAN mooring station (Sta. 51)	CTD cast (200 m).
WHOTS mooring station (Sta. 50)	CTD cast (200 m).
21° 54.1'N, 158° 16.5'W	Deployment and recovery of underwater camera.
Underway/continuous	ADCP, thermosalinograph, fluorometry, meteorology

2.0. SCIENCE PERSONNEL

Participant	Title	Affiliation/HOT Group
Karin Björkman	Research Specialist	UH/BEACH
Marina Brandon	Graduate Student	UH
Susan Curless	Research Associate	UH/BEACH
Suzanne Defelice	Research Associate	UH/PO
Stuart Donachie	Scientist	UH
Pierre Dutrieux	Graduate Student	UH/PO
Ken Doggett	Research Associate	UH/BEACH
Gabe Foreman	Marine Technician	OTG
Lance Fujieki	Computer Specialist	UH/BEACH
Eric Grabowski	Research Associate	UH/BEACH
Adriana Harlan	Technician	UH/BEACH
Kurt Heinze	Technician	UW
Paul Lethaby	Research Associate	UH/PO
Claire Mahaffey	Postdoctoral Researcher	UH/BEACH
Rex Malmstrom	Scientist	MIT
Dan Sadler	Research Associate	UH/BEACH
Fernando Santiago-Mandujano	Research Associate	UH/ PO
Justin Smith	Undergraduate Student	UH/PO
Jefrey Snyder	Marine Technician	UH/PO
Matt Sullivan	Scientist	MIT
Like Thompson	Scientist	MIT
Kuhio Vellalos	Marine Technician	OTG
Mingxi Yang	Graduate Student	UH/PO
John Yeh	Graduate Student	UH/PO
Blake Watkins	Marine Engineer	UH/BEACH

3.0. SUMMARY SCHEDULE

18 May	Pre-cruise meeting
24 May	Ship loading starting at 0900 hrs
25 May	Depart from Snug harbor at 0900 hrs. Science personnel on-board by 0830.
25 May	Station 1 Kahe Pt. operations. Deployment of underwater camera.
26-28 May	Station ALOHA operations. Stations 51 and 50 CTD casts. Recovery of underwater camera.
29 May	Arrive back to Snug harbor. ETA 0800 hrs, full offload

4.0. OPERATIONAL PLANS

4.1. Station Kahe (21°20.6'N, 158°16.4'W)

A 400 lb. weight-test cast, one CTD cast to 1000 m, and a PRR cast (Sect. 4.2.8) will be conducted at this location in the afternoon of May 25. The CTD winch and crane will be required for these operations. After the operations are satisfactorily completed, the ship shall proceed to deploy the underwater camera.

4.1.1 Deployment of free vehicle baited camera

An underwater camera consisting of a surface mast assembly and frame with Benthos floats and acoustic releases will be deployed in transit to Station ALOHA, at 21° 54.1'N, 158° 16.5'W. We request the use of the A-frame for this operation and will also use the Sea-Mac winch. This instrument will sink to the bottom of the ocean, where it will remain until its retrieval at the end of the cruise. This operation will be conducted by J. Yeh, and it will take 30 min. After this, the ship shall proceed to Station ALOHA.

4.2. Station ALOHA (22°45'N, 158°W with 6 nm radius)

4.2.1. Upon arrival to Station ALOHA, the sediment traps will be deployed. Afterwards, two 200-m casts will be conducted before deploying the Gas array. One 100-m CTD cast will be conducted after the Gas array deployment, followed by a near-bottom CTD cast.

4.2.2. Sediment trap deployment

Upon arrival to Station ALOHA, the floating sediment traps will be deployed at a location within Station ALOHA, which will be determined by local current conditions to be determined enroute to ALOHA. The array will be deployed from the stern using the A-frame and our Sea-Mac winch. Power requirement for the winch is 440 VAC, three phase at 10 amps. After deployment we request that the Bridge verify that the radio transmitters are functioning and directionally correct.

The array will drift for about 53 hours before recovery. The array is equipped with 2 ARGOS satellite transmitters (platform #s 01325 and 01833), 2 strobe lights, and 2 radio transmitters (channel 74, 156.725 MHz). Daily positions of the array shall be transmitted by email directly to the ship, therefore the ship will not need to keep within site of the array until the time of the recovery. Assistance from the bridge is requested in plotting the drift track of the array. We request the use of the ship's radio direction finder for locating the array before recovery.

After deployment of the sediment trap array, the ship shall return to the center of Station ALOHA to continue with CTD cast operations.

4.2.3 Gas Array deployment

Samples for the gas array will be collected from casts 1 and 2. We request the use of the A-frame for the gas array deployment, and will also use the Sea-Mac winch. The array is equipped with 2 ARGOS satellite transmitters, a strobe light and a radio transmitter (channel 69). The ship will **not** need to keep within sight of the array until the time of the recovery, approximately 24 hours after its deployment. CTD operations shall continue after the recovery.

4.2.4. Water column measurements

Vertical profiles of temperature, conductivity and dissolved oxygen will be made with an instrument package consisting of a Sea-Bird CTD attached to a 24-place rosette with 12 liter

sampling bottles. We need the ship's CTD winch and crane for this operation. Water samples for biogeochemical measurements will also be collected on each cast. The second cast after the deployment of the gas array (cast 4) shall be made to the near bottom (approximately 4740 m). Following this cast, a series of 1000-m casts shall be made continuously every 3 hours for a 36-hour period, ending with a second near-bottom cast. It is highly desired that this burst sampling be done without interruption and we request the ship to maintain position within the study area for that period of time, and repositioning to the center of the Station before each cast whenever possible.

Whenever pumping of the ship's tanks is needed, it must be conducted outside the circle that defines station ALOHA (Sect. 1.0). To avoid disruptions in the schedule, this operation should be coordinated with the chief scientist or the watch leaders (Eric Grabowski, Paul Lethaby).

4.2.5. Primary production experiment

Samples for the primary productivity experiment will be collected from the rosette (cast 10). Just before dawn (sunrise 0547 hrs on May 27), a second free drifting incubation array will be deployed from the stern. We request the use of the A-frame for this operation and will also use the Sea-Mac winch. The array is equipped with 2 ARGOS satellite transmitters, strobe lights and a radio transmitter (channel 72, 156.625 MHz). The ship shall keep within site of the array while performing CTD operations for the approximately 12-hour duration the array will be in the water. The array will be recovered just at sunset (1911 hrs). CTD operations shall continue after recovery. All radioactive waste generated by the experiment shall be returned to the University of Hawaii. Only qualified personnel shall handle radioactive material.

4.2.6. Plankton net tows

Plankton nets will be deployed from the stern and shall be towed for half-hour periods. Half-hour periods are scheduled at around noon and two consecutive half-hour periods at midnight on the second, third, and fourth days (see schedule) with a total of eight available slots to accommodate cancellations due to sea state or other unforeseen problems. The A-frame and capstan will be needed for this operation. B. Watkins will be in charge of these operations.

4.2.7. Automated Trace Element Sampler (ATE)

On May 26 at 1330, the ATE will be hand deployed off the back deck to a depth of 10 m. The ATE will be recovered after 30 minutes in the water. The ATE is approximately 1' tall and 4' in diameter, weighting 5 lbs.

4.2.8. Profiling Reflectance Radiometer (PRR).

Around noon on each day a profiling reflectance radiometer will be deployed from the main deck using the main crane. The instrument is hand-lowered and retrieved with assistance from the capstan.

4.2.9. AC9/FRRf

The Wet Labs AC9 is an optical instrument that measures water column spectral absorption and attenuation at nine wavelengths. The AC9 package also includes a Fast Repetition Rate Fluorometer (FRRf), and a Sea-Bird Seacat with temperature, conductivity, fluorometer, and pressure sensors. The package will be deployed to a target depth of 250 m at a

constant speed of 10 m/min during the downcast and upcast. We request the use of the ship's trawl winch and A-frame for this operation.

4.3 Floating sediment trap recovery

On May 28, after the second deep cast and other operations at Station ALOHA have been completed, we shall transit for the recovery of the floating sediment trap array. The main crane and the Sea-Mac winch will be needed to retrieve the sediment trap array. After the array is recovered, the ship shall transit to Station 51 to conduct a 200-m CTD cast.

4.4 MOSEAN Mooring (Station 51)

A 200-m CTD cast will be conducted near the MOSEAN mooring. The cast should be conducted downwind, downcurrent, and at about 200 m from the mooring. The nominal position of the mooring is 22° 45'N, 158° 6'W. After this cast, the ship shall transit to Station ALOHA to continue operations. After operations at ALOHA are completed, the ship shall transit to Station 50 to conduct one 200 m CTD cast.

4.5 WHOTS Mooring (Station 50)

One 200-m CTD cast will be conducted near the WHOTS mooring. The cast should be conducted downwind, downcurrent, and at about 200 m from the mooring. The nominal position of the mooring is 22° 46.1'N, 157° 53.4'W. After this cast is completed, the ship shall transit to retrieve the underwater camera.

4.6 Recovery of free vehicle baited camera (21° 54.1'N, 158° 16.5'W)

The underwater camera deployed at the beginning of the cruise (Sect. 4.1.1), will be recovered in the evening of May 28. The instrument's acoustic release will be triggered, and the instrument will be retrieved when it reaches the surface. We request the use of the A-frame for this operation and will also use the Sea-Mac winch. The instrument is equipped with a strobe light and a radio transmitter (channel 73, 156.675 MHz). The time for this operation will be about 2.5 hours, after which the ship shall return to Snug harbor.

4.7 Acoustic Doppler Current Profiler

The ship's acoustic Doppler current profiler (ADCP) will be in operation during the duration of the cruise. The STAG electronics technician will be in charge of the ADCP system.

4.8 Thermosalinograph and Fluorometer

The ship's thermosalinograph and fluorometer sampling the uncontaminated seawater supply system will be in operation during the duration of the cruise while the ship is outside of Snug harbor. Salinity samples to calibrate the thermosalinograph will be taken from the intake hose at 4-hour intervals throughout the duration of the cruise by the science personnel. The STAG electronics technician will be in charge of the thermosalinograph operation.

4.9 ARGO profiler floats deployment

Two ARGO profiler floats will be deployed near Sta. ALOHA by Kurt Heinze (UW, Steve Riser's group). The profilers will be hand deployed over the side of the ship on May 28, before leaving ALOHA station.

5.0 EQUIPMENT

5.1 The HOT science party shall be bringing the following

1. Seabird CTD system, all sensors, deck boxes and computer CTD acquisition systems.
2. 4 12-l water sampling bottles, all spare parts
3. Two laboratory vans with assorted equipment for radioisotope and general use
4. Distilled, deionized water and all required chemicals and isotopes
5. Storage van with assorted equipment (main deck)
6. Large vacuum waste container
7. Liquid nitrogen dewers
8. Drifting sediment trap array with strobe lights, satellite and radio transmitters, floats, weights
9. Kevlar line, polypropylene line
10. Sediment traps and crosses
11. Drifting primary production array with light and radio transmitter, floats, weights, polypro. Line, spare buoy, etc.
12. PRR, AC-9/FRRf and other optical measuring instruments.
13. Sea-Mac winch (440 VAC, 3 phase at 10 amps) and Kevlar line
14. Oxygen titration system
15. Plankton nets and towing lines
16. Desktop and laptop personal computers
17. Assorted tools
18. All required sampling bottles.
19. Deck incubation system
20. 400 lb weight.
21. Acoustic transponders for mooring release
22. Pertinent MSDS
23. Automated Trace Element Sampler (ATE)

5.2. We will need the use of the following ship's equipment:

1. A-frame and trawl winch
2. A-frame block assembly
3. Appleton crane and winch with conducting wire for CTD
4. Electric power for winches (440 VAC three phase at 10 amps) and vans (208 VAC single phase at 30 amps for labvan, 110 VAC 10 amps for equipment van)
5. Radio direction finder
6. Space on the main deck for one storage van, Sea-Mac winch
7. Space on the upper deck for two lab vans
8. Hand-held VHF transceivers
9. Precision depth recorder
10. Shackles, sheaves, hooks and lines
11. Shipboard Acoustic Doppler Current Profiler
12. Thermosalinograph and Fluorometer
13. Copy machine
14. Grappling hooks and line

15. Navlink2 PC or equivalent
16. Running fresh water and seawater, hoses
17. Electronic mail system
18. GPS system
19. Uncontaminated seawater supply
20. Capstan
21. Underway/on-station data acquisition system for meteorological instruments, ADCP, thermosalinograph, fluorometer
22. OTG's 24-place rosette, and 24 12-l water sampling bottles

Ship: R/V *KILO MOANA* **HOT 181 CTD CASTS** 25 – 29 May, 2006

Cast	Samples	#Bottles
<u>Kahe Pt.</u>		
s1c1 1000 m	O ₂ , Temp, DIC/Alk, Nuts, Chl a, LLN, LLPO ₄ , DOC, FCM, Salts	24
<u>Station ALOHA</u>		
s2c1 200 m	Gas Array (7@5, 25, 45), KB (3@30), Salts,	24
s2c2 200 m	Gas Array (7@75, 100, 125) , KB (3@30), Salts,	24
s2c3 100 m	RM (6@25, 1@45, 2@100, 1@150, 1@200)	11
s2c4 4740 m (PO-1)	O ₂ , Temp, DOC, DIC/Alk, Nuts, Salts	24
s2c5 1000 m (PO-2)	O ₂ , Temp, Nuts, DIC/Alk, Quay, DOC, Salts	24
s2c6 1000 m	ATP, Salts, MC (200,300,500,770), KB(100,125,150,175)	19
s2c7 1000 m	PE, Salts, MC(5,25,45,75,100,125,150,175), KB(5,25,45,75)	24
s2c8 1000 m	HPLC, Chl a, Slides, Salts,	22
s2c9 1000 m(BEACH)	O ₂ , Temp, DIC/Alk, Nuts, LLN, LLP, DOC, Keeling, Quay, Salts	23
s2c10 1000 m	Primary Production, CM (2@750), Salts	24
s2c11 1000 m	Open, CM(16@30), MB(2@10,2@DCM,2@700), RM(1@45, 1@100)	24
s2c12 1000 m	Open	3
s2c13 1000 m	MIT, MC(pb-5,25,45,75,100,125,150,175), SD(5,75,125,250,500,1000)	24
s2c14 1000 m	PC/PN, Salts	14
s2c15 1000 m	PPO ₄ , Salts	14
s2c16 1000 m	Open, CM(11@30,1@750), RM(1@25, 1@100, 1@150, 1@200), SD(5,75,125,250,500,1000)	22
s2c17 4740 m (PO-3)	Oxygen, Salts, MC(1@1000,2000,3000,4000), PUR	24
s2c18 200 m	RM (1@25, 1@45, 2@100, 1@150, 1@200)	6
s2c19 200 m	PSi, ZJ	22
<u>MOSEAN Mooring</u>		
s51c1 1000 m	Salts, CM(8@30,1@750) MB(1@10,1@DCM,1@700)	12
<u>WHOTS Mooring</u>		
S50c1 200 m	Salts, LB(4@5)	7

SHIP R/V *KILO MOANA*

HOT 181

DATE 25 – 29 May, 2006

TIME	Thur. 5/25	Fri. 5/26	Sat. 5/27	Sun. 5/28	Mon. 5/29
0000		S2C1 Gas 1			
0100		S2C2 Gas 2	Net Tow		
0200			S2C10 PP	Net Tow	
0300				AC9/FRRF	
0400		S2C3 (100 m)	S2C11 Open	S2C18 (200 m) Transit sed traps	
0500		Deploy gas array	Deploy PP array	Recover traps	
0600		S2C4 PO-1	Transit gas array	Transit St. 51	
0700			Recover gas array		
0800			S2C12 Open	S51C1 MOSEAN	Arrive Snug offload
0900	Depart Snug			Transit ALOHA	
1000		Net Tow	Net Tow		
1100	Arrive Kahe	S2C5 PO-2 (Begin 36 hr)	S2C13 MIT	S2C19 PSi/ZJ	
1200	Weight cast PRR		PRR AC9/FRRF	PRR AC9/FRRF	
1300	S1C1	Net Tow ATE	Net Tow	AC9/FRRF	
1400	Transit ALOHA	S2C6 ATP	S2C14 PC/PN	Transit St. 50	
1500				S50C1	
1600		Claire Net		Deploy ARGO Claire Net	
1700	Deploy camera	S2C7 PE	S2C15 PPO4	Transit retrieve camera	
1800			Recover PP array		
1900					
2000		S2C8 HPLC	S2C16 Open		
2100				Recover Camera	
2200		Net Tow	Net Tow		
2300	Arrive ALOHA Deploy sed traps	S2C9 BEACH	S2C17 PO-3 (end 36 hours)	Transit Snug	

May 27: Sunrise 0547 Sunset 1911

6.0 HOT-181 Watch Schedule

0300-1500

Fernando S-Mandujano – Chief Scientist

Jefrey Snyder

Justin Smith

Eric Grabowski – Watch Leader

Lance Fujieki

Ken Doggett

Adriana Harlan

Kurt Heinze

1500-0300

Paul Lethaby - Watch Leader

Suzanne Defelice

John Yeh

Pierre Dutrieux

Karin Björkman

Susan Curless

Dan Sadler

At Large

Blake Watkins

Claire Mahaffey

Marina Brandon

Mingxi Yang

Stuart Donachie

Rex Malmstrom

Matt Sullivan

Luke Thompson

OTG

Kuhio Vellalos

Gabe Foreman